

# **Ring Resonator Gyroscope**

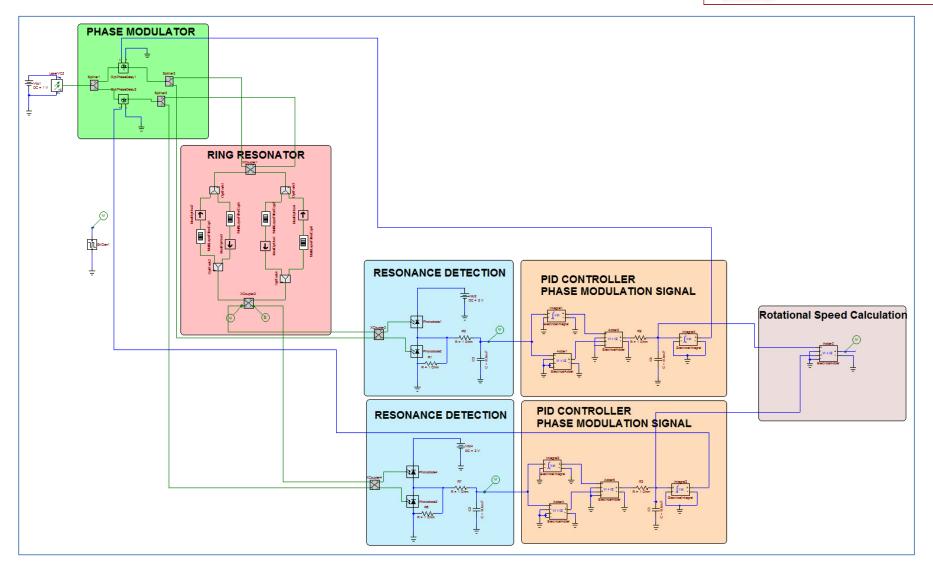


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## **Fiber Optic Gyroscope Building Blocks**









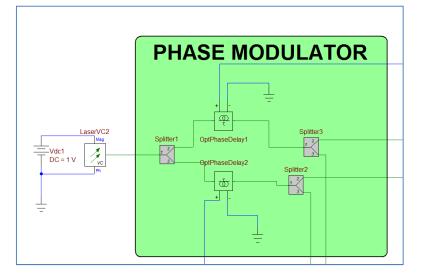
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## **Phase Modulator**



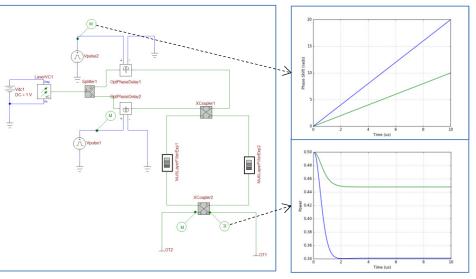
#### **Phase Modulation**

- The first splitter is used to create clockwise (CW) and counter clockwise (CCW) propagating waves in the ring resonator using a single laser source
- In OptiSPICE phase delay elements can be used to change the phase of an optical signal using a voltage node
- In this Ring Resonator Gyroscope design, phase delay elements are used to introduce a linear increase in phase over time to shift the carrier frequency of the CW and CCW propagating waves
- This frequency shift is used to keep the carrier frequency of the CW and CCW propagating waves at resonance



### Linear Phase Increase

- The simulation results show the effect of the linear increase in phase
- At time=0 the carrier frequency is equal to the resonant frequency of the ring resonator
- The introduction of the linear increase in phase over time shifts the carrier frequency of the waves travelling inside the ring resonator
- Over time, because the carrier frequencies shift towards off-resonance, the output at the drop port decreases and reaches a new steady state







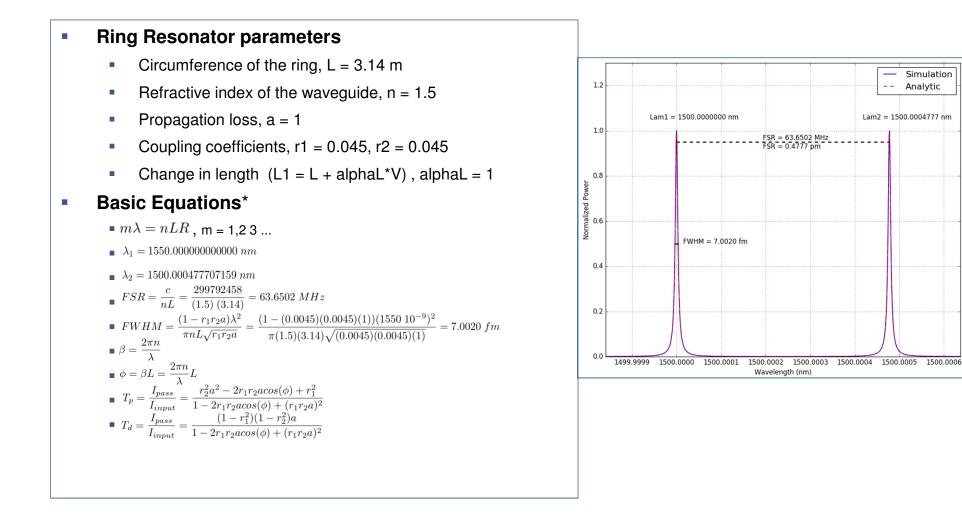




Simulation

Analytic

Lam2 = 1500.0004777 nm



\*Bogaerts, Wim, et al. "Silicon microring resonators." Laser & Photonics Reviews 6.1 (2012): 47-73.





# **Ring Resonator/Sagnac Effect**



#### **Building blocks**

- 2 Cross Couplers
- 4 Waveguides
- 4 Optical Isolators
- 4 Waveguides

#### **OptiSPICE Model**

- Explicit multilayer filter model is set up with a single layer
- The length change in the waveguide can be controlled by a voltage source
- The relationship between the length change in the waveguide and the voltage can be made linear or non-linear
- Optical Forks and Isolators are used to separate clockwise (CW) and counter clockwise (CCW) traveling signals so a different length change (due to Sagnac effect) can be applied to each signal

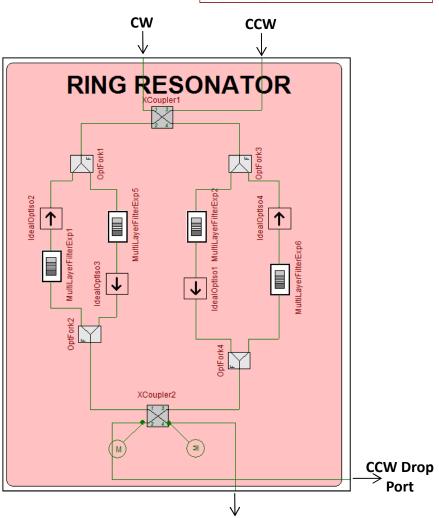
#### Sagnac Effect\*

- Number of turns, N
- Speed of light, c
- Speed of light in dielectric medium, v =
- Area of the ring resonator, A
- Rotational Speed,  $\Omega$
- The change in distance seen by CW and CCW signals,

$$\Delta L = \frac{4AN}{v}\Omega$$

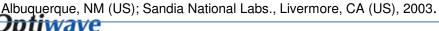
The relationship between rotational speed and change in resonant frequency is given by,

$$\Omega = \frac{nL\lambda}{4NA} \Delta f$$



\*VAWTER, GREGORY A., et al. Developments in pursuit of a micro-optic gyroscope. No. SAND2003-0665. Sandia National Labs.,

<del>Optiwave</del>





**CW Drop Port** 

### **Resonance Detection**

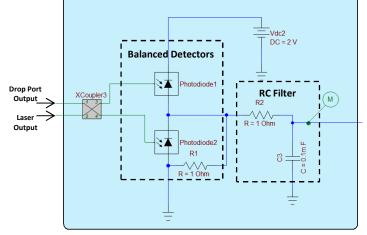


0.00 dL (um)

### Keeping the carrier at resonant frequency

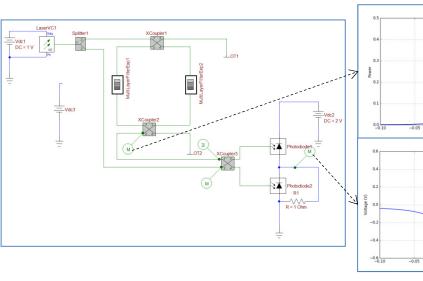
- 2 separate resonance detectors are used for CW and CCW propagating optical signals
- The output of the balanced detectors are used to drive the controller that generates the signal for phase modulation
- The RC filter following the output of the balanced detectors is used to filter out sudden changes at the output which may destabilize the circuit and cause divergence during simulation

### **RESONANCE DETECTION**



### Length vs. Detector Output

- The simulation results show the balanced detector output vs. the change in the circumference of the ring resonator
- The carrier frequency is equal to the resonant frequency of the ring resonator when dL = 0, the drop port output is at its peak and the balanced detectors are at 0 V
- The output of the balanced detectors increase/decrease as the circumference of the ring resonator increases/decreases
- The output at the drop port also decreases as the size of the circumference changes







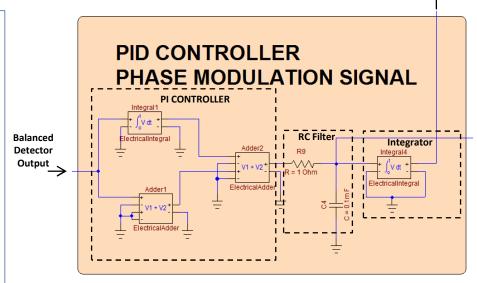
## **PID CONTROLLER**



Phase Modulator Control Signal

### **Generating Phase Modulation Signal**

- When there is a shift in resonant frequency the output of the balanced detectors shift away from 0 V
- The proportional-integral (PI) controller calculates a shift in frequency proportional the balanced detector output
- The integrator following the PI controller generates the phase modulator signal that shifts the carrier frequency going into the ring resonator
- The RC filter following the output of the PI controller is used to filter out sudden changes at the output which may destabilize the circuit and cause divergence during simulation







# **Simulation Results**



### Calculating the rotation speed

 In this example rotation speed of 3500 deg/h (0.01697 rad/s) was applied to the ring resonator by varying its circumference using the following equation,

 $\Delta L = \frac{4AN}{v} \Omega = \frac{4\pi (0.499745)^2 10}{299792458/1.5} (0.01697) = 1.1842 \ nm$ 

- The simulation results from OptiSPICE shows the output of the drop port moving back to resonance (max output) over time
- As the output of the drop port approaches resonance the balanced detector output reaches 0 due to the application of the linear phase increase by the phase modulator
- Finally the rotation speed can be calculated from the difference in resonant frequencies of CW and CCW signals using the following equation,

$$\Omega = \frac{nL\lambda}{4NA} \Delta f = \frac{(1.5)(3.14)(1550\ 10^{-9})}{4(10)(\pi)(0.49974^2)} (75.3772\ 10^3) = 3499.9995\ deg/h$$

